Side Conductive Electric Road System for Heavy-duty Trucks to EVs

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Background



Looking towards the realization of a zero- CO_2 society, it will be important to achieve zero emissions of CO_2 during vehicle operation.



The main issues facing EV are

- Driving range
- Charging (Nuisance, time, congestion at charging stations, provision of infrastructure)
- Decline in dynamic performance due to increased battery weight

Methods of Extending EV Driving Range



Electric Road Systems

(Dynamic charging system)

Road Line









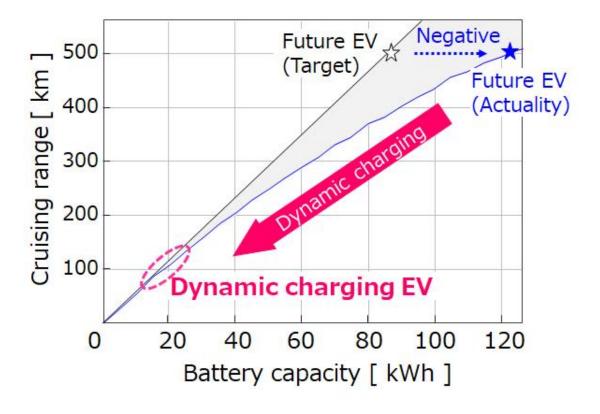
Alstom/Volvo

Elways

Elonroad

Overhead Line





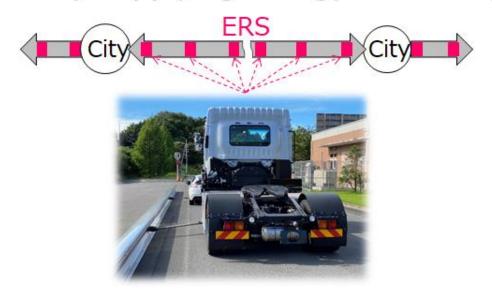
Goals of ERS Project



Goal

" Vehicle Revolution"

To extend the cruising range for EVs by enabling unlimited cruising range by simultaneously supplying energy and charging while driving.



Effects

- Unlimited vehicle cruising range
- Zero stationary charging time
- Reduced battery load (1/10)
- More enjoyable driving thanks to a lifting of the power limitations on EVs

Comparison of superiority and inferiority of ERShe Power of Dreams

3 High score 2 Medium score 1 Low score

Туре		Wireless			Conductiv <u>e</u>		
		Overhead	In-road	Side	Overhead	In-road	Side
Basic Specification	Supply power	1	1	1	3	3	3
	Vehicle speed	1	2	2	1	2	3
	Body type	1	3	2	1	3	3
Safety	Electro magnetic noise	1	1	1	3	3	3
	Foreign matter from road	3	1	2	3	1	2
	Motorcycle	1	1	1	3	1	3
Convenience	Positioning	1	1	1	2	1	3
	Emergency lane change	1	3	2	1	1	3
	Road maintenance	3	1	3	3	1	3
Cost		1	1	1	2	1	3

System Overview

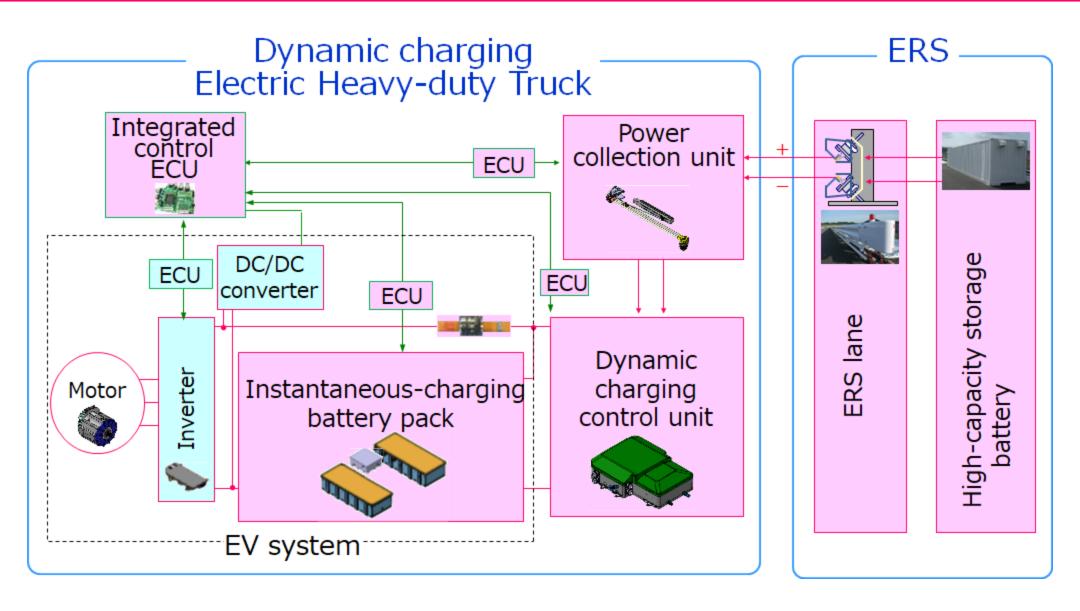


Simultaneous development of infrastructure and vehicles



Dynamic Charging System Diagram



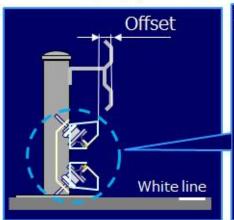


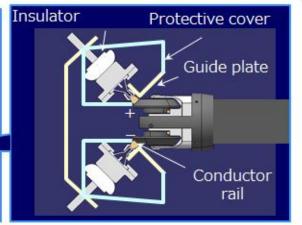
Infrastructure



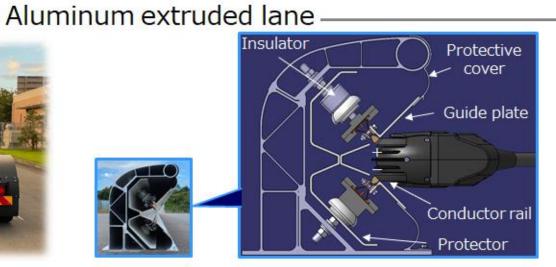










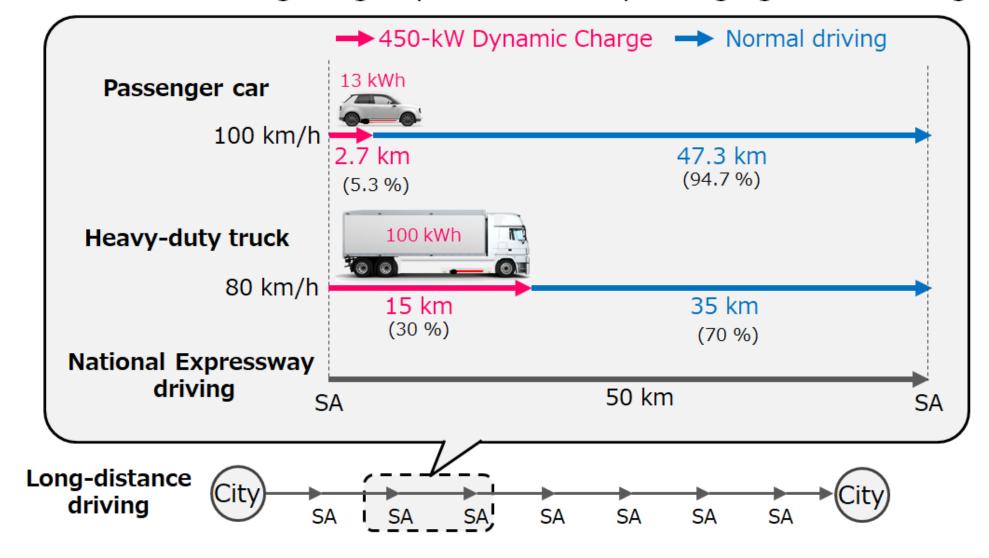




450-kW Dynamic charge driving pattern



Infinite EV cruising range by intermittently charging while driving



Prototype Systems



Туре	Type-0	Type-1	Type-2	Type-3	Type-4
Vehicle				40	C HONDA (C)
ERS power	100 kW	100 kW	180 kW	450 kW	450 kW
Power supply voltage	DC 375 V	DC 375 V	DC 600 V	DC 750 V	DC 750 V
Power supply current	300 A	300 A	300 A	600 A	600 A
Charging vehicle speed	20 km/h	70 km/h	155 km/h	150 km/h	90 km/h
Power transmission distance	0.1 - 1.2 m	0.1 - 1.2 m	0.1 - 1.3 m	0.1 - 1.3 m	0.1 - 1.5 m
ERS lane length	20 m	100 m	300 m	385 m	Over 400m (JARI)

Dynamic Charging Full-Electric Truck







Specification of Dynamic Charging Electric Heavy-duty Truck

Total vehicle weight		45.29t		
Max. load weight		38.04t		
Tractor weight		7.25t		
Max. Speed (Legal Speed)		80 km/h (Speed Limiter)		
Cruising Range		Infinite (km)		
Motor Max. Power		350 kW(476 PS)		
MOTOL	Max. Torque	3,500 N·m		
Battery	Battery Capacity	100 kWh(50kWh×2)		
	Max. Power Output	DC750 V, 600 A		
Charging Power		450 kW (DC750 V,600A)		
Dynamic Charge	Vehicle Speed	7(Creep speed)~80 km/h		
	Vehicle to Road Distance	0.1 ∼1.5 m		
	Charging distance (80 km/h while driving)	Charges 15 km (in 50 km section)		

Results of 450 kW Charging Tests



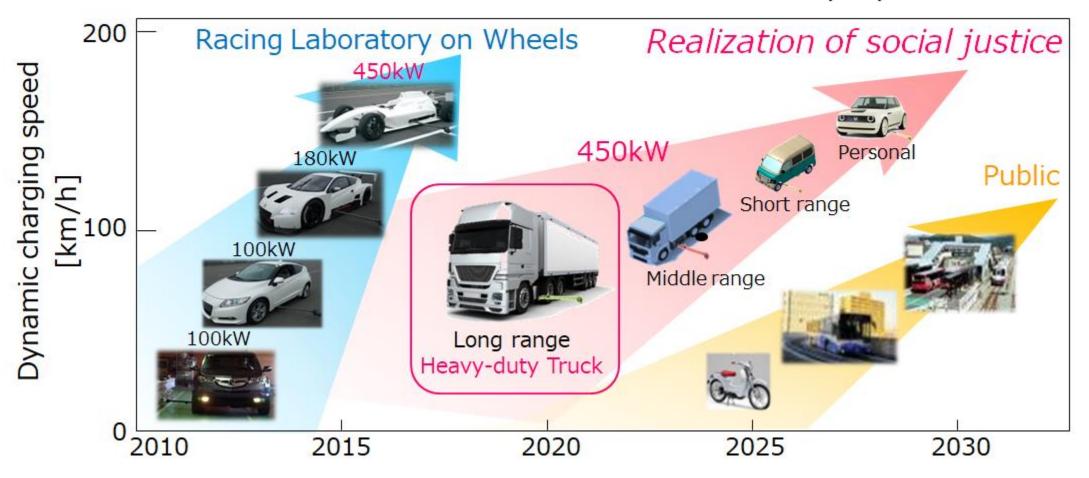
450 kW (DC 750 V, 600 A), 80 km/h



Goals of Research



Promotion of substitution of internal combustion engine vehicles and realization of carbon free society by ERS



Conclusion



Infrastructure and a vehicle system able to realize ultra-high power (450 kW, DC 750 V, 600 A) and high vehicle-speed (150 km/h) dynamic charging were developed.

The heavy-duty truck maximum motor power is 350 kW and its maximum dynamic charging speed is 80 km.

The results of dynamic charging tests conducted using a newly manufactured vehicle demonstrated that the system possessed the potential to realize the following effects:

- Remove restrictions on EV cruising range
- Reduce charge waiting time to zero
- Reduce battery weight in the vehicle (by less than 1/10)
- Increase driving pleasure by doing away with EV power restrictions

It was also shown that a 450 kW ERS would make it possible to considerably reduce battery capacity, helping to ensure the ability to supply batteries and secure resources for their manufacture.

In the future, Honda intend to continue efforts to boost the reliability and safety of the ERS, attempting to realize practical application of the system at an early stage.